



Universe Polymorphism in Coq, for the OCAML hacker

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What are universes?

Universes are the types of *types*, e.g:

- ▶ `nat, bool` : `Type0`
- ▶ `Type0` : `Type1`
- ▶ `list` : `Type0 → Type0`
- ▶ $\forall \alpha : \text{Type}_0, \text{list } \alpha : \text{Type}_1$
- ▶ $\forall n : \text{nat}, \{n = 0\} + \{n \neq 0\} : \text{Type}_0$

How are they organised?

A *hierarchy* of predicative universes $\text{Type}_0 < \text{Type}_1 < \dots$

- ▶ Avoids the $\text{Type} : \text{Type}$ paradox (system U^-)
- ▶ Replicates RUSSELL's paradox of $\{x \mid x \notin x\}$, the set of all sets etc....
- ▶ Think of Type_0 as sets, Type_1 as classes etc...

sort of t = type of the type of t , necessarily a Type_i .

$$\frac{\text{TYPE-INTRO} \quad \vdash \Gamma \quad (i \in \mathbb{N})}{\Gamma \vdash \text{Type}_i : \text{Type}_{i+1}}$$

$$\frac{\text{TYPE-PROD} \quad \Gamma \vdash A : \text{Type}_i \quad \Gamma, x : A \vdash B : \text{Type}_j}{\Gamma \vdash \Pi x : A. B : \text{Type}_{\max(i,j)}}$$

```
type Level.t
```

```
type Universe.t = (Level.t * int) list (* max([i(+n?)]) *)
```

Working with explicit universe indices is cumbersome, annotations pervade definitions and proofs.

⇒ Allow *typical ambiguity* (first used by Russell in Principia).

Idea: write **Type** to mean any type that “fits” (keeps the system consistent).

- ▶ On paper: let the reader infer levels for universes and check consistency.
- ▶ On computer: let the computer infer levels and check consistency in the background.

Floating universes

Formally, translate from **anonymous Types** to **explicit Type_i s**.
But in general many i 's can work!

Definition $\text{id} (A : \text{Type}) (a : A) := a.$

$\rightsquigarrow \vdash \text{id} : \Pi(A : \text{Type}_0), A \rightarrow A : \text{Type}_1$

or

$\rightsquigarrow \vdash \text{id} : \Pi(A : \text{Type}_1), A \rightarrow A : \text{Type}_2$

or ...?

\Rightarrow **universe variables**

```
type Level.t = Prop | Set
             | Level of int * DirPath.t (* global *)
```

Floating universes and constraints

Consistency is now ensured by giving an **assignment** of natural numbers to universe variables, satisfying *constraints*. New judgment \vdash_{float}

$$\frac{\text{TYPE-INTRO} \quad \vdash_{float} \Gamma \quad (i, j \in \mathbb{L})}{\Gamma \vdash_{float} \mathbf{Type}_i : \mathbf{Type}_j \rightsquigarrow i < j}$$

$$\frac{\text{TYPE-PROD} \quad \Gamma \vdash_{float} A : \mathbf{Type}_i \quad \Gamma, x : A \vdash B : \mathbf{Type}_j}{\Gamma \vdash_{float} \Pi x : A. B : \mathbf{Type}_k \rightsquigarrow \max(i, j) \leq k}$$

```
type constraint_type = Lt | Le | Eq
type univ_constraint = Level.t * constraint_type * Level.t
module Constraint.t : Set.S with type elt = univ_constraint
```

Type-checking generates constraints between *algebraic* universes (`Universe.t`). In the kernel (`uGraph.ml`):

- ▶ can *check* any algebraic universe constraint.
- ▶ can only *enforce* atomic constraints between levels (`Level.t`):
anomaly on non-atomic constraints.

Enforcing constraints of the form $l \leq \max(i, j)$ would require a more complex constraint checking algorithm.

Invariant: only generate constraints of the form $\max(is) \leq l$ where l is a level. `Univ.enforce_(1)eq` transforms non-atomic to atomic constraints

- ▶ Type inference naturally enforces this (subtyping rule on products being equivariant on the domain, covariant on the codomain).
- ▶ Algebraic universes can appear only at the conclusion of the term in type position of the typing judgment. So, when putting an inferred type in a term, one has to *refresh* universes (`Evarsolve.refresh_universes`). Sometimes necessary in tactics.

Floating levels provide a restricted kind of polymorphism:

Definition $\text{id} (A : \text{Type}) (a : A) := a$

$\rightsquigarrow \vdash \text{id} : \Pi(A : \text{Type}_l), A \rightarrow A : \text{Type}_{l+1}$

$\Rightarrow l$ is *not* quantified at the definition level here, it is *global*:

$\not\vdash \text{id} (\Pi(A : \text{Type}_l), A \rightarrow A) \text{id} : \tau$

Because $l + 1 \not\leq l$. However l can gradually move up as high as wanted.

Bounded polymorphism:

Polymorphic Definition $\text{id} (A : \text{Type}) (a : A) := a$

$\underline{\text{id}}_l : \Pi(A : \text{Type}_l), A \rightarrow A$

$\Rightarrow l$ is quantified at the definition level now and we can *instantiate* it at each application:

$l < k \vdash_{poly} \underline{\text{id}}_k (\Pi(A : \text{Type}_l), A \rightarrow A) \underline{\text{id}}_l : (\Pi(A : \text{Type}_l), A \rightarrow A)$

1 Introduction

2 Elaborating Universes

- Kernel
- Engine
- Unification
- Minimization

Constraint checking

Constraints are generated once at refinement time **outside** the kernel. The kernel just checks that the constraints are consistent and sufficient to typecheck the terms.

universe context	Ψ	::=	$\vec{i} \models \Theta$
<code>Univ.UContext.t</code>	=		<code>Level.t array * constraints</code>
<code>Univ.ContextSet.t</code>	=		<code>LSet.t * constraints</code>

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Elaboration in bidirectional fashion:

- ▶ Inference: $\Gamma; \Psi \vdash t \uparrow \rightsquigarrow \Psi' \vdash t' : T$
- ▶ Checking: $\Gamma; \Psi \vdash t \downarrow T \rightsquigarrow \Psi' \vdash t' : T$

Pretyping.pretype, Typing.infer, Typing.check

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`Pretyping.pretype`, `Typing.infer`, `Typing.check`

$$\frac{\text{CHECK-TYPE} \quad \theta \vdash \mathbf{Type}_{i+1} \leq T \rightsquigarrow \theta'}{\Gamma; us \models \theta \vdash \mathbf{Type} \downarrow T \rightsquigarrow us, i \models \theta' \vdash \mathbf{Type}_i : T}$$

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2 ; $\Psi \vdash t \downarrow T' \rightsquigarrow ; i \models \theta \vdash t : T'$ (infer_conv)

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- 1 $;\vdash T \uparrow \rightsquigarrow \Psi \vdash T' : s$ (pretype)
- 2 $;\Psi \vdash t \downarrow T' \rightsquigarrow; i \models \theta \vdash t : T'$ (infer_conv)
- 3 Add $\text{id} : \forall i \models \theta, T' := t$ to the environment (Typeops.infer, Reduction.conv).
- 4 If monomorphic: Add $i \models \Theta$ to the global universe environment and $\text{id} : T' := t$ separately. (Environ.push_context).

Guiding principle:

Constants are transparent, **indistinguishable** from their bodies.

Global vs local universes: i is global $\Rightarrow i > \text{Set}$, otherwise $i \geq \text{Set}$.

Using universe polymorphic definitions

$$\text{INFER-CST} \quad \frac{(\text{id} : \forall i \models \theta, T) \in \Sigma \quad \vec{l} \notin \vec{u}}{\Gamma; \vec{u} \models \Theta \vdash \text{id} \uparrow \rightsquigarrow \psi \vdash \text{id}_{\vec{l}} : T[\vec{l} / \vec{i}]}$$

$$\text{where } \psi = \vec{u}, \vec{l} \models \Theta \cup \theta[\vec{l} / \vec{i}]$$

- ⇒ Constants now carry their universe substitution/instance.
- ⇒ Inductives and constructors treated the same way.

```
type Level = Prop | Set
| Level of int * DirPath.t (* global *)
| Var of int (* local, de Bruijn index *)
```

```
type Univ.Instance.t = Level.t array
type 'a puniverses = 'a * Univ.Instance.t
```

```
type pconstant = constant puniverses
type pinductive = inductive puniverses
type pconstructor = constructor puniverses
```

```
type constr = ...
  | Sort      of Sorts.t
  | Const     of pconstant
  | Ind       of pinductive
  | Construct of pconstructor
```

$$\frac{\text{CUMUL-SORT} \quad \psi \vDash i R j}{\text{Type}_i =_{\psi}^R \text{Type}_j}$$

$$\frac{\text{CUMUL-PROD} \quad U =_{\psi}^{\equiv} U' \quad T =_{\psi}^R T'}{\Pi x : U.T =_{\psi}^R \Pi x : U'.T'}$$

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$$\frac{\text{CONV-FO} \quad \overrightarrow{as} =_{\psi}^{\equiv} \overrightarrow{bs} \quad \psi \Vdash \overrightarrow{u} = \overrightarrow{v}}{\underline{c}_{\overrightarrow{u}} \overrightarrow{as} =_{\psi}^R \underline{c}_{\overrightarrow{v}} \overrightarrow{bs}}$$

Uses **backtracking** (`Reduction.conv`)

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When elaborating terms or proofs, the inferred universe context (`evar_universe_context`, `UState.t`) is part of the `evar_map`.

```
Evd.from_env : Global.env -> evar_map
```

```
(* Gensym *)
```

```
new_univ_level_variable : ?name:string -> rigid ->  
  evar_map -> evar_map * Univ.Level.t
```

```
(* Adding constraints *)
```

```
Evd.set_leq_sort : env -> evar_map ->  
  sorts -> sorts -> evar_map
```

Use two kinds of universe level variables during elaboration:

- ▶ Polymorphic constants get elaborated with fresh **flexible** argument levels by default.
- ▶ Typical ambiguity (e.g. **Type**) creates **rigid** variables.
- ▶ User-given levels (e.g. `Type@{i}`, `foo@{i}`) are **rigid**.

```
type rigid =  
  | UnivRigid  
  | UnivFlexible of bool (* can be algebraic? *)
```

```
Evd.fresh_global : ?rigid:rigid -> env -> evar_map ->  
  global_reference -> evar_map * constr
```

```
(* For tactics *)
```

```
pf_constr_of_global : global_reference ->  
  (constr -> unit tactic) -> unit tactic
```

Unification of id_i and id_j :

Definition $U2 := \text{Type}_i$.

Definition $U1 : U2 := \text{Type}_j \rightsquigarrow j < i$

Definition $U0 : U1 := \text{Type}_k \rightsquigarrow k < j$

Definition $U02 : U2 := U0 \rightsquigarrow k < i$

$$\text{id}_j U02 \sim \text{id}_i U0 \rightsquigarrow i = j$$

But:

$$\text{id}_j U02 \rightarrow^* (U0 \rightarrow U0) \leftarrow^* \text{id}_i U0$$

Unification also backtracks to ensure most general typings.

New: also backtrack on unifications that would introduce inconsistencies (used to be found at Qed time only).

$t \equiv_{\psi}^R u \rightsquigarrow \psi'$: unification of t and u under ψ .

$$\frac{\text{ELAB-R-FO} \quad \overrightarrow{a}s \equiv_{\psi}^R \overrightarrow{b}s \rightsquigarrow \psi' \quad \psi' \models \overrightarrow{u} \equiv \overrightarrow{v} \rightsquigarrow \psi''}{\underline{c}\overrightarrow{u} \overrightarrow{a}s \equiv_{\psi}^R \underline{c}\overrightarrow{v} \overrightarrow{b}s \rightsquigarrow \psi'}$$

Unification with universes

$t \equiv_{\psi}^R u \rightsquigarrow \psi'$: unification of t and u under ψ .

$$\frac{\text{ELAB-R-FO} \quad \overrightarrow{as} \equiv_{\psi}^= \overrightarrow{bs} \rightsquigarrow \psi' \quad \psi' \models \overrightarrow{u} \equiv \overrightarrow{v} \rightsquigarrow \psi''}{\underline{c}_{\overrightarrow{u}} \overrightarrow{as} \equiv_{\psi}^R \underline{c}_{\overrightarrow{v}} \overrightarrow{bs} \rightsquigarrow \psi'}$$

$\psi \models i \equiv j \rightsquigarrow \psi'$: unification of universe instances.

$$\frac{\text{ELAB-UNIV-EQ} \quad \psi \models i = j}{\psi \models i \equiv j \rightsquigarrow \psi}$$

$$\frac{\text{ELAB-UNIV-FLEXIBLE} \quad i_f \vee j_f \in \overrightarrow{u}_s \quad \psi \wedge i = j \models}{(\overrightarrow{u}_s \models \psi) \models i \equiv j \rightsquigarrow \psi \wedge i = j}$$

Universe instances are levels: Suppose

$$\text{id} : \forall i \vDash, \Pi A : \text{Type}_i, A \rightarrow A$$

$$\Gamma = A : \text{Type}_i, P : \text{fibration}_{i,j} A \vdash \Sigma_{ij} A P : \text{Type}_{\max(i,j)}$$

Levels only, adding constraint if an algebraic would appear:

$$\Gamma; \vec{u} \vDash \theta \vdash \text{id} (\Sigma A P) \uparrow \vec{u}, k \vDash \theta \cup \max(i, j) \leq k \vdash \text{id}_k (\Sigma_{ij} A P) \dots$$

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Levels only, adding constraint if an algebraic would appear:

$$\Gamma; \vec{u} \models \theta \vdash \text{id} (\Sigma A P) \uparrow \vec{u}, k \models \theta \cup \max(i, j) \leq k \vdash \text{id}_k (\Sigma_{ij} A P) \dots$$

That's *a lot* of fresh universe variables!!

Typical example:

$$\Gamma; \vdash \text{id } \text{true} \uparrow \rightsquigarrow i_f \vDash \text{Set} \leq i \vdash @i_{i_f} \text{ bool } \text{true} : \text{bool}$$

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⇒ Minimization: compute a minimal set of universe variables.

See Cardelli's greedy algorithm for F^{\leq} inference, local type inference (Pierce & Turner).

- ▶ **Only** applies to flexible variables.

Before putting a definition/proof term into the environment:

```
Evd.nf_constraints : evar_map -> evar_map
```

```
Evarutil.nf_evars_universes :  
  evar_map -> constr -> constr
```

```
Evd.universe_context : ?names -> evar_map ->  
  (Id.t * Level.t) list * Univ.universe_context
```

Which comparison function to use? (e.g. for `change`, `Ltac` pattern-matching, ...)

- ▶ Syntactic equality: `eq_constr_nounivs`, `eq_constr_univs`, `eq_constr_univs_infer`
- ▶ Conversion: `Reductionops.check_conv`, `infer_conv`
- ▶ Unification: `evar_conv_x` (no choice here)

We chose to use `infer` versions most of the time, assuming universe unifications are wanted. This required fixing threadings of the `evar_map`.

Due to obligation to register levels and constraints in the `evvar_map`, and as `global_references` are no longer well-formed `constrs` (except monomorphic ones):

- ▶ Tactics should bind lazy `global_references` instead of lazy `constrs`.
- ▶ `Term.eq_constr` should be rare in tactics, many cases where `Globnames.is_global` should be used instead.
- ▶ Tactics need to ensure the terms they produce can be typed in the `evvar_map` (e.g. with sufficient universe constraints). Otherwise use checked versions (e.g. `exact_check`) that do typechecking to ensure the constraints are inferred.

Universes must be declared before they are used:

- ▶ Problem with side-effect e.g. of `Require Import` during a proof. Must explicitly update the `evvar_map` of the proof with the new constraints. Would be fixed by correctly threading the env in proof mode, with side effecting commands emitting their effects in that env.
- ▶ In tactics, any `evvar_map` threading error can result in an anomaly.

The main issue is the large number of universes and constraints generated (100's for a single definition).

- ▶ Cumulativity going through inductives (A. Timany), and definitions.
- ▶ Try to classify argument universes as inputs and outputs (syntactic check), and treat inputs like “template” polymorphic universes, not recording them. Looses compositionality: must check complete applications of polymorphic references.
- ▶ More algebraic universes, less constraints. Algebraics need heuristics in unification: $\max(i, j) = \max(k, l)$? (Agda, Lean have incomplete solutions). If one keeps non-normalized $\max(-)$ universes, we can maybe avoid heuristics but make $\max(-)$ expressions grow a lot.

At the end of elaboration: $\vec{i} \models \Theta \vdash t : T$, with θ a satisfiable set of constraints.

Find a minimal set of universes variables $\vec{i}' \subset \vec{i}$, universes \vec{u} , a substitution $\sigma : \vec{i} \rightarrow \vec{u}$ and constraints Θ' s.t. $\vec{i}' \models \Theta' \cup \Theta\sigma$ and $\vec{i}' \models \Theta\sigma \Rightarrow \Theta'$.

- First normalize the constraints w.r.t. loops ($l \leq r \wedge r \leq l$) and equalities.

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- ▶ First normalize the constraints w.r.t. loops ($l \leq r \wedge r \leq l$) and equalities.
- ▶ Canonicalize Θ w.r.t equalities (except globals)
- ▶ Consider the remaining undefined flexible universe variables.

We now have Θ with only inequality constraints and a set f of flexible universe variables.

- ▶ Let $i \in f$, compute its g.l.b: $\{\max(\vec{j}), j \mid i \in \Theta\}$. If i has no lower constraints it must be kept.
- ▶ Generate upper constraints $\{glb \mid i \in \Theta\}$
- ▶ Set $i := glb$ except if glb is algebraic and i has upper constraints.

